

# Team Cambridge Technology: Bestrack#1

## Itemized Remaining Technical Challenges

1. **Milestone#1**: Develop More Mature Motion Profiling Mathematics
  - 1.1. Research current methodologies for controlled acceleration profiling. **(Evan)**
  - 1.2. Define rapid math-based algorithms for generating velocity slopes based on smooth acceleration parameters. **(Evan)**
  - 1.3. Design an algorithm to translate the generated trajectory profiles into pulse-count and pulse-period pairs, to eventually be delivered to the FPGA fabric. **(Evan)**
  - 1.4. Fully test and adjust the above theoretical basis for motion profiling in a controlled environment with the linear slide. **(Joint)**
2. **Milestone#2**: Implement High-Level Motor Control and Define API
  - 2.1. Research and test data transfer/delivery from bare-metal core to FPGA modules (AXI communication). **(Joint)**
  - 2.2. Modify FPGA hardware to receive pulse-count and pulse-period pairs and convert them into dynamic step-and-direction signals for propagation to the stepper motor. **(Evan)**
  - 2.3. Implement the trajectory profiling algorithms of Milestone#1. **(Alec)**
  - 2.4. Design basic test codes to ensure the validity and effectiveness of the high level control. **(Alec)**
3. **Milestone#3**: Fully Integrate Into SMC Architecture
  - 3.1. Working with the Technical Directors, establish a better understanding of how to interface with the Linux core, and how our work will be best integrated. **(Joint)**
  - 3.2. Develop device driver code to activate the motion control algorithms and actuate the step-and-direction logic. **(Alec)**
  - 3.3. Based on the feedback from 3.1, follow through with porting our code and driving software into the full-scale system. **(Alec)**
  - 3.4. Test that our code is still operational, even under more complex or non ideal situations. **(Evan)**
4. **Milestone#4**: Finalize Demonstration to Exercise the API
  - 4.1. Working with the Technical Directors and their equipment, define an exhaustive test application in abstract terms to demonstrate the robustness of our work. **(Joint)**
  - 4.2. Implement the above application and confirm successful/desirable operation with the Technical Directors. **(Alec)**
  - 4.3. Finalize documentation and ensure our code is well defined, organized, and easily passed off to any engineer. **(Joint)**

## 1.1. Project Execution Roadmap

<b>Week</b>	<b>Dates Spring 2023</b>	<b>Items to be Worked on</b>	<b>Anticipated Milestone Completion</b>
1	1/24 - 1/30	1.1, 2.1	
2	1/31 - 2/06	1.2, 1.3, 2.1, 2.2	
3	2/07 - 2/13	1.2, 1.3, 2.3, 2.4	
4	2/14 - 2/20	1.4, 2.4	Milestone#2
5	2/21 - 2/27	1.4	
6	2/28- 3/06	1.4, 3.1	Milestone#1
7	3/07 - 3/12	3.1, 3.2, 3.3	
8	Spring Break		
9	3/21 - 3/27	3.2, 3.3, 3.4	
10	3/28 - 4/03	3.4, 4.1	Milestone#3
11	4/04 - 4/10	4.2	
12	4/11 - 4/16	4.3	Milestone#4

Add sections for further technical details, questions etc. (see template starting on next Page)

**Further Details on Key Technical Accomplishments and RESULTS: (Identify Designer)**

**Schedule Assessment: (If behind schedule, indicate plan to get back on schedule)**

**Important Questions for Technical Directors**